

R88M-K□

Accurax G5 servo motors

**Servo family for accurate motion control.
High response, high speed and high torque.**

- Peak torque 300% of rated torque during 3 seconds or more depending on model
- High resolution serial encoder provided by 20 bits encoder
- IP67 protection in all models
- Ultra-light and compact size motor
- Low speed ripple and low torque ripple due to low torque cogging
- Various shaft, brake and seal options

Ratings

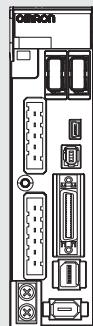
- 230 VAC from 50 W to 1.5 kW
(rated torque from 0.16 to 8.59 Nm)
- 400 VAC from 400 W to 5 kW
(rated torque from 1.91 Nm to 28.7 Nm)



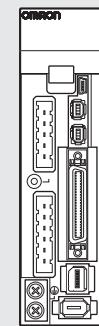
System configuration

(Refer to servo drive chapter)

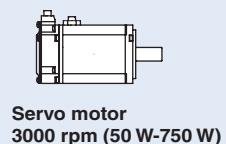
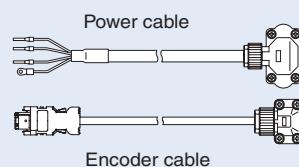
Drive options



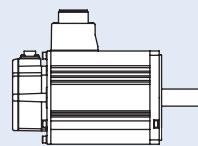
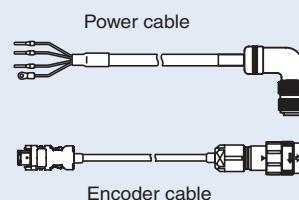
MECHATROLINK-II
models



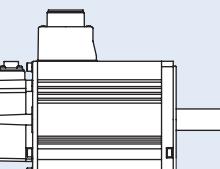
Analog/Pulse
models



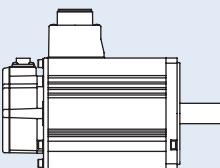
Servo motor
3000 rpm (50 W-750 W)



Servo motor
3000 rpm (1 kW-5 kW)



Servo motor
2000 rpm (400 W-5 kW)



Servo motor
1000 rpm (900 W-3 kW)

Servo motor / servo drive combination

Accurax G5 rotary servo motor					Accurax G5 servo drive					
	Voltage	Speed	Rated torque	Capacity	Model	MECHATROLINK-II model		Analog/Pulse model		
						230 V	400 V	230 V	400 V	
	230 V	3000 min ⁻¹	0.16 Nm	50 W	R88M-K05030(H/T)-□	R88D-KN01H-ML2	-	R88D-KT01H	-	
			0.32 Nm	100 W	R88M-K10030(H/T)-□	R88D-KN01H-ML2	-	R88D-KT01H	-	
			0.64 Nm	200 W	R88M-K20030(H/T)-□	R88D-KN02H-ML2	-	R88D-KT02H	-	
			1.3 Nm	400 W	R88M-K40030(H/T)-□	R88D-KN04H-ML2	-	R88D-KT04H	-	
			2.4 Nm	750 W	R88M-K75030(H/T)-□	R88D-KN08H-ML2	-	R88D-KT08H	-	
	400 V		3.18 Nm	1000 W	R88M-K1K030(H/T)-□	R88D-KN15H-ML2	-	R88D-KT15H	-	
			4.77 Nm	1500 W	R88M-K1K530(H/T)-□	R88D-KN15H-ML2	-	R88D-KT15H	-	
			2.39 Nm	750 W	R88M-K75030(F/C)-□	-	R88D-KN10F-ML2	-	R88D-KT10F	
			3.18 Nm	1000 W	R88M-K1K030(F/C)-□	-	R88D-KN15F-ML2	-	R88D-KT15F	
			4.77 Nm	1500 W	R88M-K1K530(F/C)-□	-	R88D-KN15F-ML2	-	R88D-KT15F	
	230 V		6.37 Nm	2000 W	R88M-K2K030(F/C)-□	-	R88D-KN20F-ML2	-	R88D-KT20F	
			9.55 Nm	3000 W	R88M-K3K030(F/C)-□	-	R88D-KN30F-ML2	-	R88D-KT30F	
			12.7 Nm	4000 W	R88M-K4K030(F/C)-□	-	R88D-KN50F-ML2	-	R88D-KT50F	
			15.9 Nm	5000 W	R88M-K5K030(F/C)-□	-	R88D-KN50F-ML2	-	R88D-KT50F	
			4.77 Nm	1000 W	R88M-K1K020(H/T)-□	R88D-KN10H-ML2	-	R88D-KT10H	-	
	400 V		7.16 Nm	1500 W	R88M-K1K520(H/T)-□	R88D-KN15H-ML2	-	R88D-KT15H	-	
			1.91 Nm	400 W	R88M-K40020(F/C)-□	-	R88D-KN06F-ML2	-	R88D-KT06F	
			2.86 Nm	600 W	R88M-K60020(F/C)-□	-	R88D-KN06F-ML2	-	R88D-KT06F	
			4.77 Nm	1000 W	R88M-K1K020(F/C)-□	-	R88D-KN10F-ML2	-	R88D-KT10F	
			7.16 Nm	1500 W	R88M-K1K520(F/C)-□	-	R88D-KN15F-ML2	-	R88D-KT15F	
	230 V		9.55 Nm	2000 W	R88M-K2K020(F/C)-□	-	R88D-KN20F-ML2	-	R88D-KT20F	
			14.3 Nm	3000 W	R88M-K3K020(F/C)-□	-	R88D-KN30F-ML2	-	R88D-KT30F	
	400 V		19.1 Nm	4000 W	R88M-K4K020(F/C)-□	-	R88D-KN50F-ML2	-	R88D-KT50F	
			23.9 Nm	5000 W	R88M-K5K020(F/C)-□	-	R88D-KN50F-ML2	-	R88D-KT50F	
	230 V	1000 min ⁻¹	8.59 Nm	900 W	R88M-K90010(H/T)-□	R88D-KN15H-ML2	-	R88D-KT15H	-	
			8.59 Nm	900 W	R88M-K90010(F/C)-□	-	R88D-KN15F-ML2	-	R88D-KT15F	
	400 V		19.1 Nm	2000 W	R88M-K2K010(F/C)-□	-	R88D-KN30F-ML2	-	R88D-KT30F	
			28.7 Nm	3000 W	R88M-K3K010(F/C)-□	-	R88D-KN50F-ML2	-	R88D-KT50F	

Note: 1. For servo motor and cables part numbers refer to ordering information at the end of this chapter
 2. Refer to the servo drive chapter for drive options selection and detailed specifications

Servo motor type designation

Servo motor

R88M-K05030H-BOS2

Accurax G5 Series Servomotor

Capacity

050	50 W
100	100 W
200	200 W
400	400 W
600	600 W
750	750 W
900	900 W
1K0	1 kW
1K5	1.5 kW
2K0	2 kW
3K0	3 kW
4K0	4 kW
5K0	5 kW

Rated Speed (r/min)

10	1000
20	2000
30	3000

Shaft end specifications

Blank	Straight shaft, no key
S2	Straight, key, tapped (standard)

Oil seal specifications

Blank	No oil seal
O	Oil seal

Brake specifications

Blank	No brake
B	Brake

Voltage and encoder specifications

H: 230 V and 20-bit incremental encoder

T: 230 V and 17-bit absolute encoder

F: 400 V and 20-bit incremental encoder

C: 400 V and 17-bit absolute encoder

Servo motor specifications

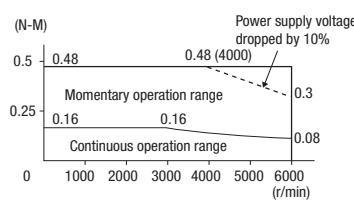
Servo motors 3000 r/min, 230 V

Ratings and specifications

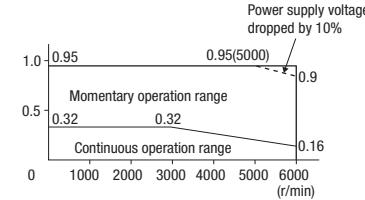
Voltage		230 V										
Servo motor model R88M-K	20-bit incremental encoder	05030H	10030H	20030H	40030H	75030H	1K030H	1K530H				
	17-bit absolute encoder	05030T	10030T	20030T	40030T	75030T	1K030T	1K530T				
Rated output	W	50	100	200	400	750	1000	1500				
Rated torque	N·m	0.16	0.32	0.64	1.3	2.4	3.18	4.77				
Instantaneous peak torque	N·m	0.48	0.95	1.91	3.8	7.1	9.55	14.3				
Rated current	A (rms)	1.2	1.1	1.5	2.4	4.1	6.6	8.2				
Instantaneous max. current	A (rms)	5.1	4.7	6.5	10.2	17.4	28	35				
Rated speed	min ⁻¹				3000							
Max. speed	min ⁻¹			6000			5000					
Torque constant	N·m/A (rms)	0.11±10%	0.21±10%	0.31±10%	0.39±10%	0.42±10%	0.37	0.45				
Rotor moment of inertia (JM)	kg·m ² ×10 ⁻⁴ (without brake)	0.025	0.051	0.14	0.26	0.87	2.03	2.84				
	kg·m ² ×10 ⁻⁴ (with brake)	0.027	0.054	0.16	0.28	0.97	2.35	3.17				
Allowable load moment of inertia (JL)	Multiple of (JM)			30			20	15				
Rated power rate	kW/s (without brake)	10.1	19.9	29.0	62.4	65.6	49.8	80.1				
	kW/s (with brake)	9.4	18.8	25.4	58	58.8	43	71.8				
Allowable radial load	N		68		245		490					
Allowable thrust load	N		58		98		196					
Approx. mass	Kg (without brake)	0.32	0.47	0.82	1.2	2.3	3.5	4.4				
	Kg (with brake)	0.53	0.68	1.3	1.7	3.1	4.5	5.4				
Brake specifications	Rated voltage	24VDC ±10%										
	Holding brake moment of inertia J	kg·m ² ×10 ⁻⁴	0.002	0.0018			0.33					
	Power consumption (at 20°C)	W	7	9	17	19						
	Current consumption (at 20°C)	A	0.3	0.36	0.70±10%	0.81±10%						
	Static friction torque	N·m (minimum)	0.29	1.27	2.5	7.8						
	Rise time for holding torque	ms (max.)	35		50							
	Release time	ms (max.)	20		15							
Basic specifications	Time Rating	Continuous										
	Insulation class	Type B			Type F							
	Ambient operating/ storage temperature	0 to +40°C/ -20 to 65°C										
	Ambient operating/ storage humidity	20 to 80% (non-condensing)			20 to 85% (non-condensing)							
	Vibration class	V-15										
	Insulation resistance	20 MΩ min. at 500 VDC between the power terminals and FG terminal										
	Enclosure	Totally-enclosed, self-cooling, IP67 (excluding shaft opening)										
Vibration resistance		Vibration acceleration 49 m/s ²										
	Mounting	Flange-mounted										

Torque-speed characteristics

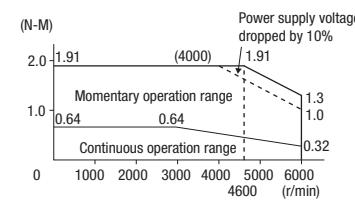
R88M-K05030H/T (50 W)



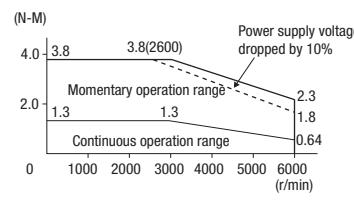
R88M-K10030H/T (100 W)



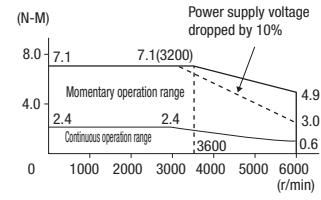
R88M-K20030H/T (200 W)



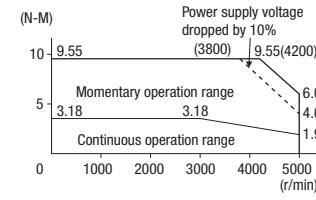
R88M-K40030H/T (400 W)



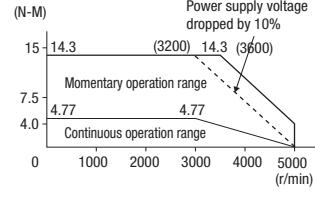
R88M-K75030H/T (750 W)



R88M-K1K030H/T (1 kW)



R88M-K1K530H/T (1.5 kW)



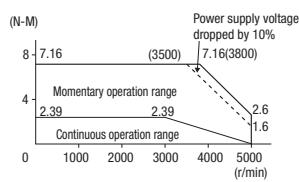
Servo motors 3000 r/min, 400 V

Ratings and specifications

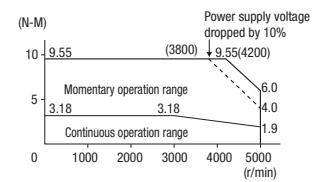
Voltage		400 V													
Servo motor model R88M-K	20-bit incremental encoder	75030F	1K030F	1K530F	2K030F	3K030F	4K030F	5K030F							
	17-bit absolute encoder	75030C	1K030C	1K530C	2K030C	3K030C	4K030C	5K030C							
Rated output	W	750	1000	1500	2000	3000	4000	5000							
Rated torque	N·m	2.39	3.18	4.77	6.37	9.55	12.7	15.9							
Instantaneous peak torque	N·m	7.16	9.55	14.3	19.1	28.6	38.2	47.7							
Rated current	A (rms)	2.4	3.3	4.2	5.7	9.2	9.9	12							
Instantaneous max. current	A (rms)	10	14	18	24	39	42	51							
Rated speed	min ⁻¹				3000										
Max. speed	min ⁻¹			5000			4500								
Torque constant	N·m/A (rms)	0.78	0.75	0.89	0.87	0.81		0.98							
Rotor moment of inertia (JM)	kg·m ² ×10 ⁻⁴ (without brake)	1.61	2.03	2.84	3.68	6.5	12.9	17.4							
	kg·m ² ×10 ⁻⁴ (with brake)	1.93	2.35	3.17	4.01	7.85	14.2	18.6							
Allowable load moment of inertia (JL)	Multiple of (JM)			30											
Rated power rate	kW/s (without brake)	35.5	49.8	80.1	110	140	126	146							
	kW/s (with brake)	29.6	43	71.8	101	116	114	136							
Allowable radial load	N			490			784								
Allowable thrust load	N			196			343								
Approx. mass	Kg (without brake)	3.1	3.5	4.4	5.3	8.3	11	14							
	Kg (with brake)	4.1	4.5	5.4	6.3	9.4	12.6	16							
Basic specifications	Rated voltage	24VDC±10%													
	Holding brake moment of inertia J/kg·m ² ×10 ⁻⁴			0.33			1.35								
	Power consumption (at 20°C)	W	17	19			22								
	Current consumption (at 20°C)	A	0.70±10%	0.81±10%			0.90±10%								
	Static friction torque	N·m (minimum)	2.5	7.8	11.8		16.1								
	Rise time for holding torque	ms (max.)		50			110								
	Release time	ms (max.)		15			50								
	Time Rating	Continuous													
	Insulation class	Type F													
Ambient operating/ storage temperature 0 to +40°C/ -20 to 65°C															
Ambient operating/ storage humidity 20% to 85% (non-condensing)															
Vibration class V-15															
Insulation resistance 20 MΩ min. at 500 VDC between the power terminals and FG terminal															
Enclosure Totally-enclosed, self-cooling, IP67(excluding shaft opening)															
Vibration resistance Vibration acceleration 49 m/s ²															
Mounting Flange-mounted															

Torque-speed characteristics

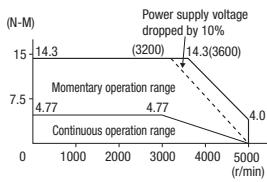
R88M-K75030F/C (750 W)



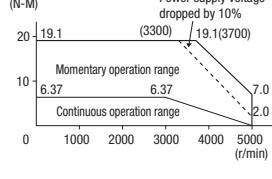
R88M-K1K030F/C (1 kW)



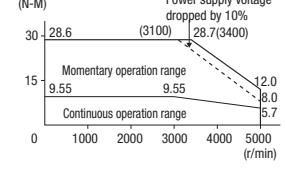
R88M-K1K530F/C (1.5 kW)



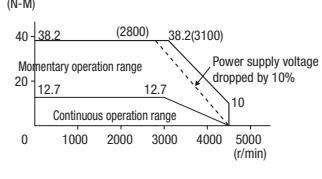
R88M-K2K030F/C (2 kW)



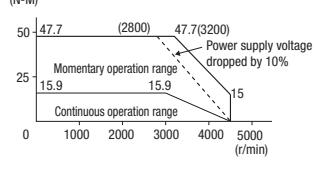
R88M-K3K030F/C (3 kW)



R88M-K4K030F/C (4 kW)



R88M-K5K030F/C (5 kW)



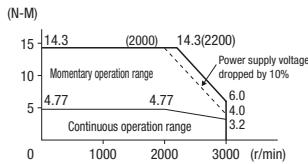
Servo motors 2000 r/min, 230V/ 400 V

Ratings and specifications

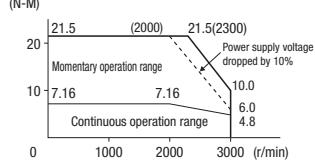
Voltage	230 V				400 V						
Servo motor model R88M-K	20-bit incremental encoder	1K020H-□	1K520H-□	40020F-□	60020F-□	1K020F-□	1K520F-□	2K020F-□	3K020F-□	4K020F-□	5K020F-□
	17-bit absolute encoder	1K020T-□	1K520T-□	40020C-□	60020C-□	1K020C-□	1K520C-□	2K020C-□	3K020C-□	4K020C-□	5K020C-□
Rated output	W	1000	1500	400	600	1000	1500	2000	3000	4000	5000
Rated torque	N·m	4.77	7.16	1.91	2.86	4.77	7.16	9.55	14.3	19.1	23.9
Instantaneous peak torque	N·m	14.3	21.5	5.73	8.59	14.3	21.5	28.7	43	57.3	71.6
Rated current	A (rms)	5.7	9.4	1.2	1.5	2.8	4.7	5.9	8.7	10.6	13
Instantaneous max. current	A (rms)	24	40	4.9	6.5	12	20	25	37	45	55
Rated speed	min ⁻¹							2000			
Max. speed	min ⁻¹							3000			
Torque constant	N·m/A (rms)	0.63	0.58	1.27	1.38	1.27	1.16	1.27	1.18	1.40	1.46
Rotor moment of inertia (JM)	kg·m ² ×10 ⁻⁴ (without brake)	4.60	6.70	1.61	2.03	4.60	6.70	8.72	12.9	37.6	48
	kg·m ² ×10 ⁻⁴ (with brake)	5.90	7.99	1.90	2.35	5.90	7.99	10	14.2	38.6	48.8
Max. load moment of inertia (JL)	Multiple of (JM)							10			
Rated power rate	kW/s (without brake)	49.5	76.5	22.7	40.3	49.5	76.5	105	159	97.1	119
	kW/s (with brake)	38.6	64.2	19.2	34.8	38.6	64.2	91.2	144	94.5	117
Allowable radial load	N					490				784	
Allowable thrust load	N					196				343	
Approx. mass	kg (without brake)	5.2	6.7	3.1	3.5	5.2	6.7	8	11	15.5	18.6
	kg (with brake)	6.7	8.2	4.1	4.5	6.7	8.2	9.5	12.6	18.7	21.8
Rated voltage	24VDC ±10%										
Holding brake moment inertia	(J) kg·m ² ×10 ⁻⁴					1.35				4.7	
Power consumption (20°C)	W	14	19	17	14	19	22			31	
Current consumption (20°C)	A	0.59±10%	0.79±10%	0.70±10%	0.59±10%	0.79±10%	0.90±10%	1.3±10%	1.3±10%		
Static friction torque	N·m (minimum)	4.9	13.7	2.5	4.9	13.7	16.2			24.5	
Rise time for holding torque	ms (max.)	80	100	50	80	100	110			80	
Release time	ms (max.)	70	50	15	70	50				25	
Time Rating	Continuous										
Insulation class	Type F										
Ambient operating/ storage temperature	0 to +40 °C / -20 to 85°C										
Ambient operating/ storage humidity	20% to 85% (non-condensing)										
Vibration class	V-15										
Insulation resistance	20 MΩ min. at 500 VDC between the power terminals and FG terminal										
Enclosure	Totally-enclosed, self-cooling, IP67 (excluding shaft opening)										
Vibration resistance	Vibration acceleration 49 m/s ²										
Mounting	Flange-mounted										

Torque-speed characteristics

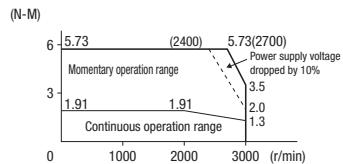
R88M-K1K020H/T (230V, 1 kW)



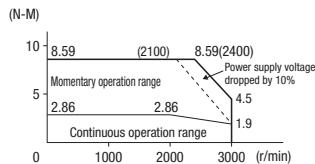
R88M-K1K520H/T (230V, 1.5 kW)



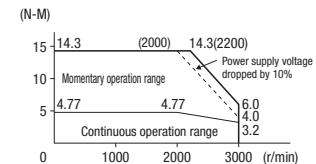
R88M-K40020F/C (400V, 400 W)



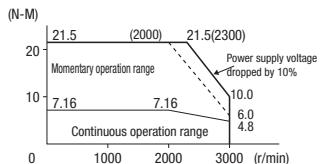
R88M-K60020F/C (400V, 600 W)



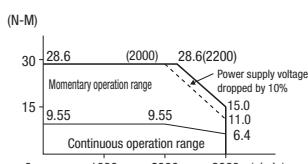
R88M-K1K020F/C (400V, 1 kW)



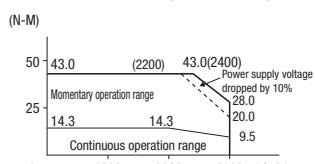
R88M-K1K520F/C (400V, 1.5 kW)



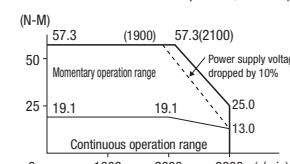
R88M-K2K020F/C (400V, 2 kW)



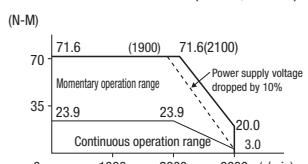
R88M-K3K0F/C (400V, 3 kW)



R88M-K4K020F/C (400V, 4 kW)



R88M-K5K020F/C (400V, 5 kW)



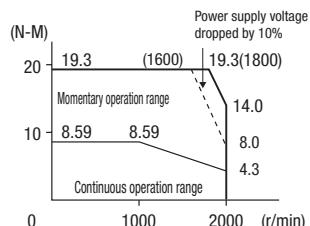
Servo motors 1000 r/min, 230V/ 400 V

Ratings and specifications

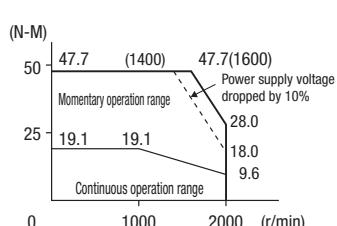
Applied voltage		230 V	400 V		
Servo motor model R88M-K	20-bit incremental encoder	90010H-	90010F-	2K010F-	3K010F-
	17-bit absolute encoder	90010T-	90010C-	2K010C-	3K010C-
Rated output	W	900	900	2000	3000
Rated torque	N·m	8.59	19.3	19.1	28.7
Instantaneous peak torque	N·m		19.3	47.7	71.7
Rated current	A (rms)	7.6	3.8	8.5	11.3
Instantaneous max. current	A (rms)	24	12	30	40
Rated speed	min ⁻¹		1000		
Max. speed	min ⁻¹		2000		
Torque constant	N·m/A (rms)	0.86	1.72	1.76	1.92
Rotor moment of inertia (JM)	kg·m ² ×10 ⁻⁴ (without brake)	6.70		30.3	48.4
	kg·m ² ×10 ⁻⁴ (with brake)	7.99		31.4	49.2
Allowable load moment of inertia (JL)	Multiple of (JM)		10		
Rated power rate	kW/s (without brake)	110	120	170	
	kW/s (with brake)	92.4	116	167	
Allowable radial load	N	686	1176	1470	
Allowable thrust load	N	196		490	
Approx. mass	kg (without brake)	6.7	14	20	
	kg (with brake)	8.2	17.5	23.5	
Brake specifications	Rated voltage	24VDC ±10%			
	Holding brake moment of inertia J	kg·m ² ×10 ⁻⁴	1.35		4.7
	Power consumption (at 20°C)	W	19	31	34
	Current consumption (at 20°C)	A	0.79±10%	1.3±10%	1.4±10%
	Static friction torque	N·m (minimum)	13.7	24.5	58.8
	Rise time for holding torque	ms (max.)	100	80	150
	Release time	ms (max.)	50	25	50
Basic specifications	Time Rating	Continuous			
	Insulation class	Type F			
	Ambient operating/ storage temperature	0 to +40 °C/ -20 to 65°C			
	Ambient operating/ storage humidity	20% to 85% RH (non-condensing)			
	Vibration class	V-15			
	Insulation resistance	20 MΩ min. at 500 VDC between the power terminals and FG terminal			
	Enclosure	Totally-enclosed, self-cooling, IP67 (excluding shaft opening)			
Vibration resistance		Vibration acceleration 49 m/s ²			
Mounting		Flange-mounted			

Torque-speed characteristics

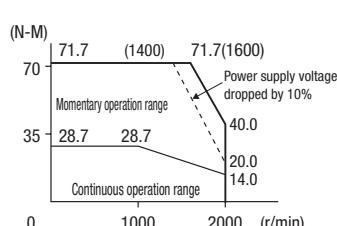
R88M-K90010H/T/F/C



R88M-K2K010F/C



R88M-K3K010F/C

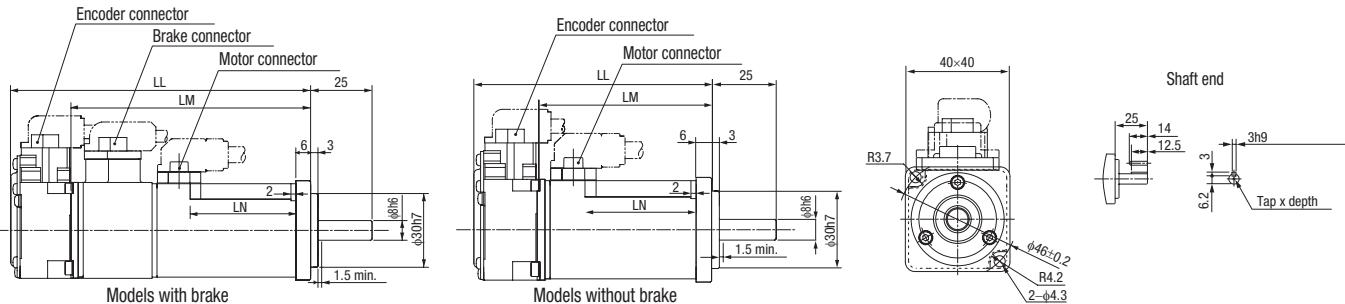


Dimensions

Servomotors

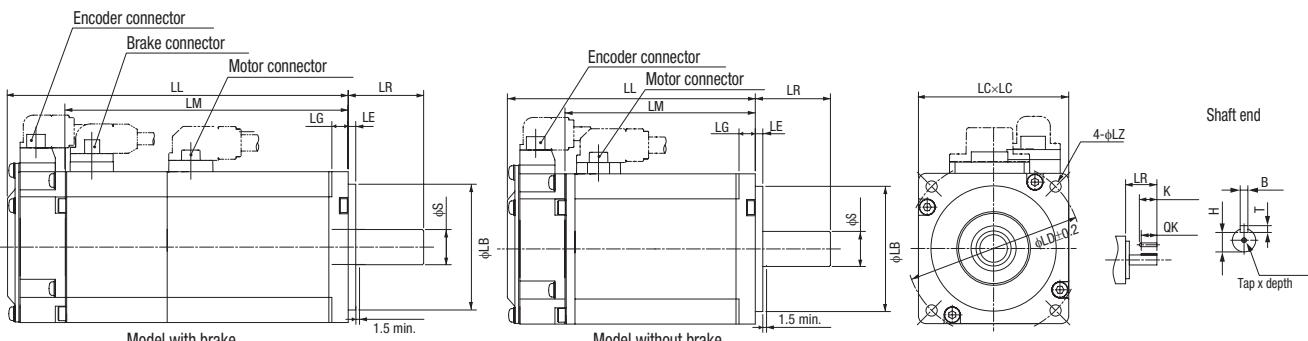
Type 3000 r/min motors (230 V, 50 - 100 W)

Dimensions (mm)	Without brake		With brake		LN	Shaft End Dimensions		Approx. Mass (Kg)	
	LL	LM	LL	LM		Tap × Depth	Without brake	With brake	
R88M-K05030(H/T)-□S2	72	48	102	78	23	M3x6L		0.32	0.53
R88M-K10030(H/T)-□S2	92	68	122	98		43		0.47	0.68



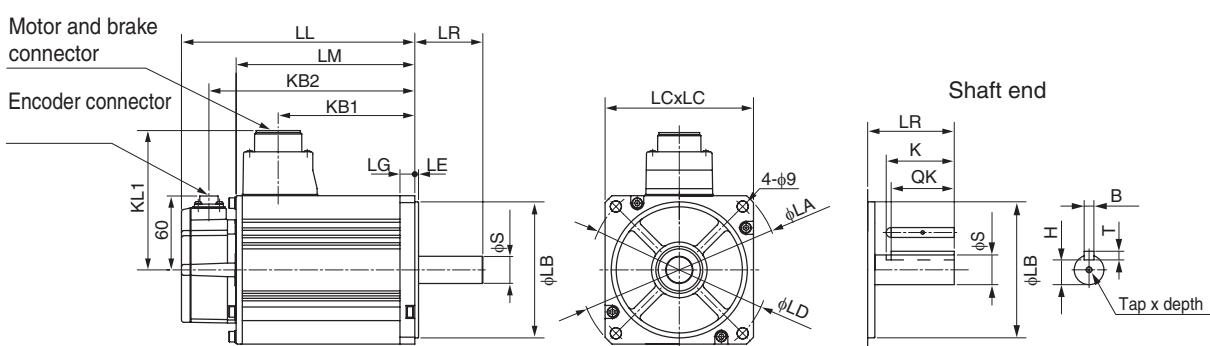
Type 3000 r/min motors (230 V, 200 - 750 W)

Dimensions (mm)	Without brake		With brake		LR	Flange surface					Shaft End Dimensions					Approx. Mass Kg					
	LL	LM	LL	LM		LB	LC	LD	LE	LG	LZ	S	K	QK	H	B	T	Tap × Depth	Without brake	With brake	
R88M-K20030(H/T)-□S2	79.5	56.5	116	93	30	50 ^{h7}	60	70	3	6.5	4.5	11 ^{h6}	20	18	8.5	4 ^{h9}	4	M4x8L	0.82	1.3	
R88M-K40030(H/T)-□S2	99	76	135.5	112.5								14 ^{h6}	25	22.5	11	5 ^{h9}	5	M5x10L	1.2	1.7	
R88M-K75030(H/T)-□S2	112.2	86.2	148.2	122.2	35	70 ^{h7}	80	90		8	6	19 ^{h6}			22	15.5	6 ^{h9}	6		2.3	3.1



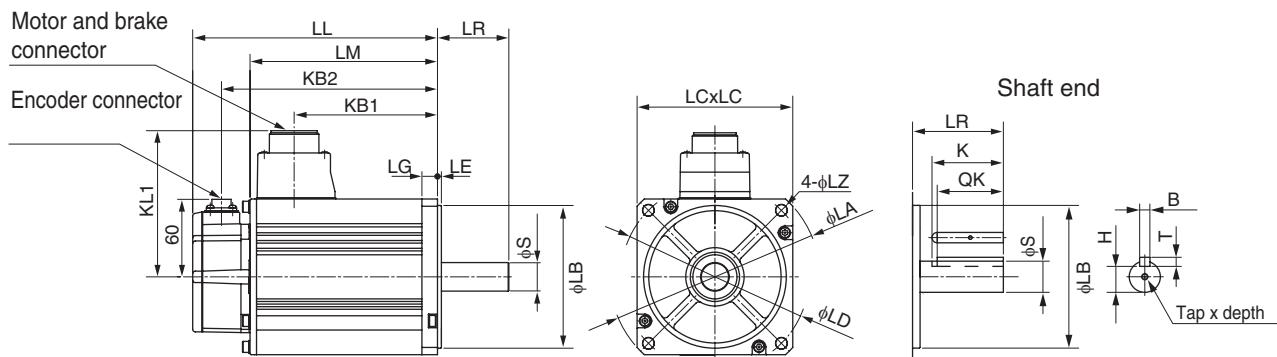
Type 3000 r/min motors (230 V, 1 - 1.5 kW/ 400V, 750 W - 5 kW)

Voltage	Dimensions (mm)	Without brake					With brake					LR	Flange surface					Shaft End Dimensions					Approx. Mass (kg)				
		Model	LL	LM	KB1	KB2	KL1	LL	LM	KB1	KB2	KL1	LA	LB	LC	LD	LE	LG	S	Tap x Depth	K	QK	H	B	T	Without brake	With brake
230	1K030(H/T)-□S2	141	97	66	119	101	168	124	66	146	101	55	135	95 ^{h7}	100	115	3	10	19 ^{h6}	M5x12L	45	42	15.5	6 ^{h9}	6	3.5	4.5
	1K530(H/T)-□S2	159.5	115.5	84.5	137.5		186.5	142.5	84.5	164.5																4.4	5.4
400	75030(F/C)-□S2	131.5	87.5	56.5	109.5		158.5	114.5	53.5	136.5	103															3.1	4.1
	1K030(F/C)-□S2	141	97	66	119		168	124	63	146																3.5	4.5
	1K530(F/C)-□S2	159.5	115.5	84.5	137.5		186.5	142.5	81.5	164.5															4.4	5.4	
	2K030(F/C)-□S2	178.5	134.5	103.5	156.5		205.5	161.5	100.5	183.5															5.3	6.3	
	3K030(F/C)-□S2	190	146	112	168	113	215	171	112	193	113		162	110 ^{h7}	120	145	6	12	22 ^{h6}		41	18	8 ^{h9}	7	8.3	9.4	
	4K030(F/C)-□S2	208	164	127	186	118	233	189	127	211	118	65	165		130				24 ^{h6}	M8x20L	55	51	20		11	12.6	
	5K030(F/C)-□S2	243	199	162	221		268	224	162	246																14	16



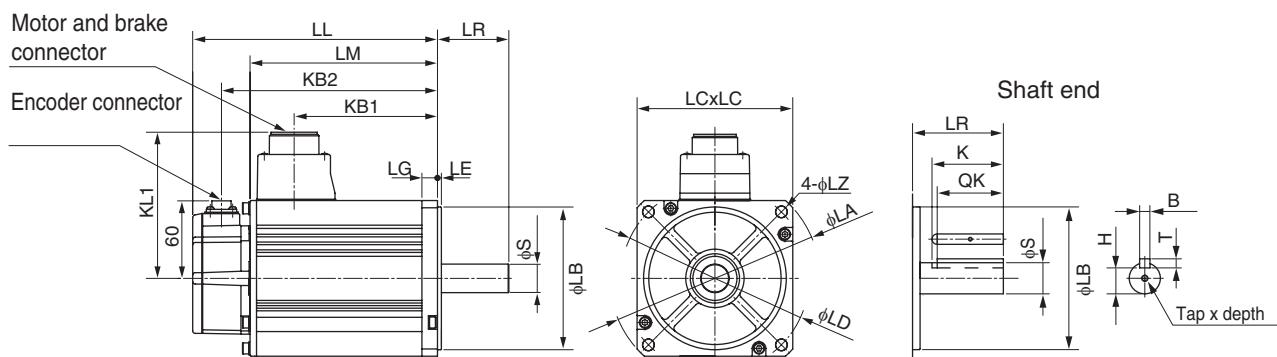
Type 2000 r/min motors (230 V, 1 - 1.5 kW / 400 V, 400W - 5 kW)

Dimensions (mm)		Without brake					With brake					LR	Flange surface						Shaft End Dimensions					Approx. Mass (Kg)									
Voltage	Model	LL	LM	KB1	KB2	KL1	LL	LM	KB1	KB2	KL1		LA	LB	LC	LD	LE	LG	LZ	S	Tap x Depth	K	QK	H	B	T	Without brake	With brake					
230	R88M-K□	138	94	60	116	116	163	119	60	141	116	55	165	110 ^{h7}	130	145	6	12	9	22 ^{h6}	M5x12L	45	41	18	8 ^{h9}	7	5.2	6.7					
	1K020(H/T)-□S2	155.5	111.5	77.5	133.5		180.5	136.5	77.5	158.5			135	95 ^{h7}	100	115	3	10		19 ^{h6}		42	15.5	6 ^{h9}	6	3.1	4.1						
400	40020(F/C)-□S2	131.5	87.5	56.5	109.5	101	158.5	114.5	53.5	136.5	103		165	110 ^{h7}	130	145	6	12		22 ^{h6}		41	18	8 ^{h9}	7	5.2	6.7						
	60020(F/C)-□S2	141	97	66	119		168	124	63	146			198	154	92	176				24 ^{h6}	M8x20L	55	51	20		6	3.5	4.5					
	1K020(F/C)-□S2	138	94	60	116	116	163	119	57	141	118		202	158	96	180	140	70	233	114.3 ^{h7}	176	200	3.2	18	13.5	35 ^{h6}	M12x25L	50	30	10 ^{h9}	8	15.5	18.7
	3K020(F/C)-□S2	173	129	95	151		198	154	92	176			221	177	115	199											11	12.6	18.6	21.8			
	4K020(F/C)-□S2	177	133	96	155	140	202	158	96	180	140		221	177	115	199																	
	5K020(F/C)-□S2	196	152	115	174																												



Type 1000 r/min motors (230 V, 900W / 400 V, 900W - 3 kW)

Dimensions (mm)		Without brake					With brake					LR	Flange surface						Shaft End Dimensions					Approx. Mass (Kg)				
Voltage	Model	LL	LM	KB1	KB2	KL1	LL	LM	KB1	KB2	KL1		LA	LB	LC	LD	LE	LG	LZ	S	Tap x Depth	K	QK	H	B	T	Without brake	With brake
230	R88M-K□	155.5	111.5	77.5	133.5	116	180.5	136.5	77.5	158.5	116	70	165	110 ^{h7}	130	145	6	12	9	22 ^{h6}	M5x12L	45	41	18	8 ^{h9}	7	6.7	8.2
400	90010(F/C)-□S2	163.5	119.5	82.5	141.5	140	188.5	144.5	82.5	166.5	140	80	233	114.3 ^{h7}	176	200	3.2	18	13.5	35 ^{h6}	M12x25L	55	50	30	10 ^{h9}	8	14	17.5
	2K010(F/C)-□S2	163.5	119.5	82.5	141.5	140	188.5	144.5	82.5	166.5	140		234.5	190.5	128.5	212.5										20	23.5	
	3K010(F/C)-□S2	209.5	165.5	128.5	187.5																							

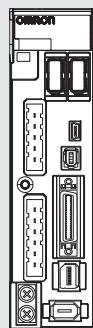


Ordering information

(Refer to servo drive chapter)

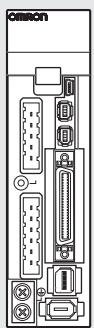
Drive options

②

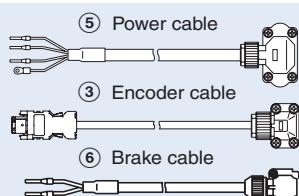


MECHATROLINK-II
models

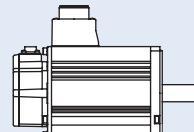
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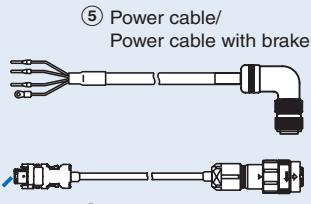
Analog/Pulse
models



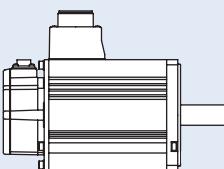
① Servo motor
3000 rpm (50 W-750 W)



① Servo motor
3000 rpm (1 kW-5 kW)



① Servo motor
2000 rpm (400 W-5 kW)



① Servo motor
1000 rpm (900 W-3 kW)

Note: The symbols ①②③... show the recommended sequence to select the servo motor and cables

Servo motor

① Select motor from R88M-K family using motor tables in next pages.

Servo drive

② Refer to Accurax G5 servo drive chapter for detailed drive specifications and selection of drive accessories.

Servo motors 3000 r/min (50 - 5000 W)

Symbol	Specifications				Servo motor model	Compatible servo drives (2)		
	Voltage	Encoder and design	Rated torque	Capacity		G5 MECHATROLINK-II	G5 Analog/Pulse	
(1) 230 V (50 - 750 W) 230 V (1000 - 1500 W) 400 V (750 - 5000 W)	230 V	Incremental encoder (20 bit) Straight shaft with key and tap	Without brake	0.16 Nm	50 W	R88M-K05030H-S2	R88D-KN01H-ML2	R88D-KT01H
				0.32 Nm	100 W	R88M-K10030H-S2	R88D-KN01H-ML2	R88D-KT01H
				0.64 Nm	200 W	R88M-K20030H-S2	R88D-KN02H-ML2	R88D-KT02H
				1.3 Nm	400 W	R88M-K40030H-S2	R88D-KN04H-ML2	R88D-KT04H
			With brake	2.4 Nm	750 W	R88M-K75030H-S2	R88D-KN08H-ML2	R88D-KT08H
				3.18 Nm	1000 W	R88M-K1K030H-S2	R88D-KN15H-ML2	R88D-KT15H
				4.77 Nm	1500 W	R88M-K1K530H-S2	R88D-KN15H-ML2	R88D-KT15H
				0.16 Nm	50 W	R88M-K05030H-BS2	R88D-KN01H-ML2	R88D-KT01H
		Absolute encoder (17 bit) Straight shaft with key and tap	Without brake	0.32 Nm	100 W	R88M-K10030T-S2	R88D-KN01H-ML2	R88D-KT01H
				0.64 Nm	200 W	R88M-K20030T-S2	R88D-KN02H-ML2	R88D-KT02H
				1.3 Nm	400 W	R88M-K40030T-S2	R88D-KN04H-ML2	R88D-KT04H
				2.4 Nm	750 W	R88M-K75030T-S2	R88D-KN08H-ML2	R88D-KT08H
			With brake	3.18 Nm	1000 W	R88M-K1K030T-S2	R88D-KN15H-ML2	R88D-KT15H
				4.77 Nm	1500 W	R88M-K1K530T-S2	R88D-KN15H-ML2	R88D-KT15H
				0.16 Nm	50 W	R88M-K05030T-BS2	R88D-KN01H-ML2	R88D-KT01H
				0.32 Nm	100 W	R88M-K10030T-BS2	R88D-KN01H-ML2	R88D-KT01H
400 V	400 V	Incremental encoder (20 bit) Straight shaft with key and tap	Without brake	0.64 Nm	200 W	R88M-K20030F-S2	R88D-KN02H-ML2	R88D-KT02H
				1.3 Nm	400 W	R88M-K40030F-S2	R88D-KN04H-ML2	R88D-KT04H
				2.4 Nm	750 W	R88M-K75030F-S2	R88D-KN08H-ML2	R88D-KT08H
				3.18 Nm	1000 W	R88M-K1K030F-S2	R88D-KN15H-ML2	R88D-KT15H
			With brake	4.77 Nm	1500 W	R88M-K1K530F-S2	R88D-KN15H-ML2	R88D-KT15H
				6.37 Nm	2000 W	R88M-K2K030F-S2	R88D-KN20F-ML2	R88D-KT20F
				9.55 Nm	3000 W	R88M-K3K030F-S2	R88D-KN30F-ML2	R88D-KT30F
				12.7 Nm	4000 W	R88M-K4K030F-S2	R88D-KN50F-ML2	R88D-KT50F
		Absolute encoder (17 bit) Straight shaft with key and tap	Without brake	15.9 Nm	5000 W	R88M-K5K030F-S2	R88D-KN50F-ML2	R88D-KT50F
				2.39 Nm	750 W	R88M-K75030F-S2	R88D-KN10F-ML2	R88D-KT10F
				3.18 Nm	1000 W	R88M-K1K030F-S2	R88D-KN15F-ML2	R88D-KT15F
				4.77 Nm	1500 W	R88M-K1K530F-S2	R88D-KN15F-ML2	R88D-KT15F
			With brake	6.37 Nm	2000 W	R88M-K2K030F-S2	R88D-KN20F-ML2	R88D-KT20F
				9.55 Nm	3000 W	R88M-K3K030F-S2	R88D-KN30F-ML2	R88D-KT30F
				12.7 Nm	4000 W	R88M-K4K030F-S2	R88D-KN50F-ML2	R88D-KT50F
				15.9 Nm	5000 W	R88M-K5K030F-S2	R88D-KN50F-ML2	R88D-KT50F
		Absolute encoder (17 bit) Straight shaft with key and tap	With brake	2.39 Nm	750 W	R88M-K75030C-S2	R88D-KN10F-ML2	R88D-KT10F
				3.18 Nm	1000 W	R88M-K1K030C-S2	R88D-KN15F-ML2	R88D-KT15F
				4.77 Nm	1500 W	R88M-K1K530C-S2	R88D-KN15F-ML2	R88D-KT15F
				6.37 Nm	2000 W	R88M-K2K030C-S2	R88D-KN20F-ML2	R88D-KT20F
			Without brake	9.55 Nm	3000 W	R88M-K3K030C-S2	R88D-KN30F-ML2	R88D-KT30F
				12.7 Nm	4000 W	R88M-K4K030C-S2	R88D-KN50F-ML2	R88D-KT50F
				15.9 Nm	5000 W	R88M-K5K030C-S2	R88D-KN50F-ML2	R88D-KT50F
				2.39 Nm	750 W	R88M-K75030C-BS2	R88D-KN10F-ML2	R88D-KT10F

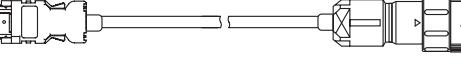
Servo motors 2000 r/min (1 - 5 kW)

Symbol	Specifications				Servo motor model	Compatible servo drives (2)	
	Voltage	Encoder and design	Rated torque	Capacity		G5 MECHATROLINK-II	G5 Analog/Pulse
①	230 V	Incremental encoder (20 bit)	Without brake	4.77 Nm	1000 W	R88M-K1K020H-S2	R88D-KN10H-ML2
			7.16 Nm	1500 W	R88M-K1K520H-S2	R88D-KN15H-ML2	
		Straight shaft with key and tap	Without brake	4.77 Nm	1000 W	R88M-K1K020H-BS2	R88D-KN10H-ML2
			7.16 Nm	1500 W	R88M-K1K520H-BS2	R88D-KN15H-ML2	
		Absolute encoder (17 bit)	Without brake	4.77 Nm	1000 W	R88M-K1K020T-S2	R88D-KN10H-ML2
			7.16 Nm	1500 W	R88M-K1K520T-S2	R88D-KN15H-ML2	
		Straight shaft with key and tap	Without brake	4.77 Nm	1000 W	R88M-K1K020T-BS2	R88D-KN10H-ML2
			7.16 Nm	1500 W	R88M-K1K520T-BS2	R88D-KN15H-ML2	
	400 V	Incremental encoder (20 bit)	Without brake	1.91 Nm	400 W	R88M-K40020F-S2	R88D-KN06F-ML2
			2.86 Nm	600 W	R88M-K60020F-S2	R88D-KN06F-ML2	
		Straight shaft with key and tap	Without brake	4.77 Nm	1000 W	R88M-K1K020F-S2	R88D-KN10F-ML2
			7.16 Nm	1500 W	R88M-K1K520F-S2	R88D-KN15F-ML2	
		Absolute encoder (17 bit)	Without brake	9.55 Nm	2000 W	R88M-K2K020F-S2	R88D-KN20F-ML2
			14.3 Nm	3000 W	R88M-K3K020F-S2	R88D-KN30F-ML2	
		Straight shaft with key and tap	Without brake	19.1 Nm	4000 W	R88M-K4K020F-S2	R88D-KN50F-ML2
			23.9 Nm	5000 W	R88M-K5K020F-S2	R88D-KN50F-ML2	
		Incremental encoder (20 bit)	With brake	1.91 Nm	400 W	R88M-K40020F-BS2	R88D-KN06F-ML2
			2.86 Nm	600 W	R88M-K60020F-BS2	R88D-KN06F-ML2	
		Absolute encoder (17 bit)	With brake	4.77 Nm	1000 W	R88M-K1K020F-BS2	R88D-KN10F-ML2
			7.16 Nm	1500 W	R88M-K1K520F-BS2	R88D-KN15F-ML2	
		Incremental encoder (20 bit)	Without brake	9.55 Nm	2000 W	R88M-K2K020C-S2	R88D-KN20F-ML2
			14.3 Nm	3000 W	R88M-K3K020C-S2	R88D-KN30F-ML2	
		Straight shaft with key and tap	Without brake	19.1 Nm	4000 W	R88M-K4K020C-S2	R88D-KN50F-ML2
			23.9 Nm	5000 W	R88M-K5K020C-S2	R88D-KN50F-ML2	
		Absolute encoder (17 bit)	Without brake	1.91 Nm	400 W	R88M-K40020C-S2	R88D-KN06F-ML2
			2.86 Nm	600 W	R88M-K60020C-S2	R88D-KN06F-ML2	
		Straight shaft with key and tap	Without brake	4.77 Nm	1000 W	R88M-K1K020C-S2	R88D-KN10F-ML2
			7.16 Nm	1500 W	R88M-K1K520C-S2	R88D-KN15F-ML2	
		Incremental encoder (20 bit)	With brake	9.55 Nm	2000 W	R88M-K2K020C-BS2	R88D-KN20F-ML2
			14.3 Nm	3000 W	R88M-K3K020C-BS2	R88D-KN30F-ML2	
		Straight shaft with key and tap	With brake	19.1 Nm	4000 W	R88M-K4K020C-BS2	R88D-KN50F-ML2
			23.9 Nm	5000 W	R88M-K5K020C-BS2	R88D-KN50F-ML2	

Servo motors 1000 r/min (900 - 3000 W)

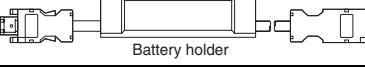
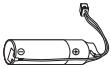
Symbol	Specifications				Servo motor model	Compatible servo drives (2)	
	Voltage	Encoder and design	Rated torque	Capacity		G5 MECHATROLINK-II	G5 Analog/Pulse
①	230 V	Incremental encoder (20 bit)	Without brake	8.59 Nm	900 W	R88M-K90010H-S2	R88D-KN15H-ML2
			Straight shaft with key and tap	8.59 Nm	900 W	R88M-K90010H-BS2	R88D-KT15H
		Absolute encoder (17 bit)	Without brake	8.59 Nm	900 W	R88M-K90010T-S2	R88D-KN15H-ML2
			Straight shaft with key and tap	8.59 Nm	900 W	R88M-K90010T-BS2	R88D-KT15H
		Incremental encoder (20 bit)	Without brake	8.59 Nm	900 W	R88M-K90010F-S2	R88D-KN15F-ML2
			19.1 Nm	2000 W	R88M-K2K010F-S2	R88D-KN30F-ML2	
			28.7 Nm	3000 W	R88M-K3K010F-S2	R88D-KN50F-ML2	
			With brake	8.59 Nm	900 W	R88M-K90010F-BS2	R88D-KN15F-ML2
	400 V	Incremental encoder (20 bit)	Without brake	19.1 Nm	2000 W	R88M-K2K010F-BS2	R88D-KN30F-ML2
			28.7 Nm	3000 W	R88M-K3K010F-BS2	R88D-KN50F-ML2	
		Absolute encoder (17 bit)	Without brake	8.59 Nm	900 W	R88M-K90010C-S2	R88D-KN15F-ML2
			19.1 Nm	2000 W	R88M-K2K010C-S2	R88D-KN30F-ML2	
		Straight shaft with key and tap	Without brake	28.7 Nm	3000 W	R88M-K3K010C-S2	R88D-KN50F-ML2
			With brake	8.59 Nm	900 W	R88M-K90010C-BS2	R88D-KN15F-ML2
			19.1 Nm	2000 W	R88M-K2K010C-BS2	R88D-KN30F-ML2	
			28.7 Nm	3000 W	R88M-K3K010C-BS2	R88D-KN50F-ML2	

Encoder cables**for absolute and incremental encoders**

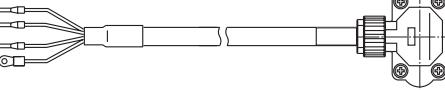
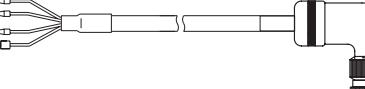
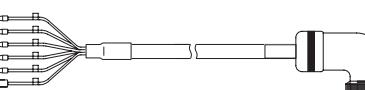
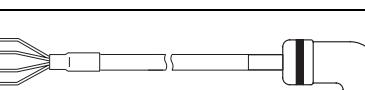
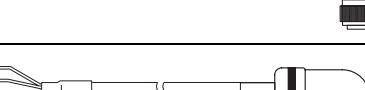
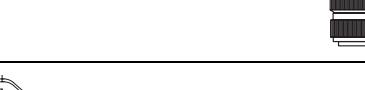
Symbol	Specifications	Model	Appearance
(3)	Encoder cable for servomotors R88M-K(050/100/200/400/750)30(H/T)□	1.5 m R88A-CRKA001-5CR-E 3 m R88A-CRKA003CR-E 5 m R88A-CRKA005CR-E 10 m R88A-CRKA010CR-E 15 m R88A-CRKA015CR-E 20 m R88A-CRKA020CR-E	
	Encoder cable for servomotors R88M-K(1K0/1K5)30(H/T)□ R88M-K(750/1K0/1K5/2K0/3K0/4K0/5K0)30(F/C)□ R88M-K(400/600/1K0/1K5/2K0/3K0/4K0/5K0)20□ R88M-K(900/2K0/3K0)10□	1.5 m R88A-CRKC001-5NR-E 3 m R88A-CRKC003NR-E 5 m R88A-CRKC005NR-E 10 m R88A-CRKC010NR-E 15 m R88A-CRKC015NR-E 20 m R88A-CRKC020NR-E	

Note: For servomotors fitted with an absolute encoder you have to add the extension battery cable R88A-CRGD0R3C□ (see below) or connect a backup battery in the CN1 I/O connector.

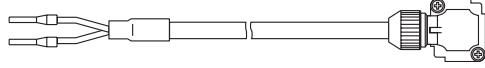
Absolute encoder battery cable (encoder extension cable only)

Symbol	Specifications	Model	Appearance
(4)	Absolute encoder battery cable	Battery not included 0.3 m R88A-CRGD0R3C Battery included (R88A-BAT01G) 0.3 m R88A-CRGD0R3C-BS	 Battery holder
	Absolute encoder backup battery	2,000 mA.h 3.6V - R88A-BAT01G	

Power cables

Symbol	Specifications	Model	Appearance
(5)	For 200 V servomotors R88M-K(050/100/200/400/750)30(H/T)□	Power cable only (without brake) 1.5 m R88A-CAKA001-5SR-E 3 m R88A-CAKA003SR-E 5 m R88A-CAKA005SR-E 10 m R88A-CAKA010SR-E 15 m R88A-CAKA015SR-E 20 m R88A-CAKA020SR-E	
	Note: for servomotors with brake R88M-K(050/100/200/400/750)30(H/T)-BS2, the separate brake cable R88A-CAKA□□□BR-E is needed	without brake □-S2 1.5 m R88A-CAGB001-5SR-E 3 m R88A-CAGB003SR-E 5 m R88A-CAGB005SR-E 10 m R88A-CAGB010SR-E 15 m R88A-CAGB015SR-E 20 m R88A-CAGB020SR-E	
		with brake □-BS2 1.5 m R88A-CAGB001-5BR-E 3 m R88A-CAGB003BR-E 5 m R88A-CAGB005BR-E 10 m R88A-CAGB010BR-E 15 m R88A-CAGB015BR-E 20 m R88A-CAGB020BR-E	
	For 400 V servomotors R88M-K(750/1K0/1K5/2K0)30(F/C)□ R88M-K(400/600/1K0/1K5/2K0)20(F/C)□ R88M-K90010(F/C)□	without brake □-S2 1.5 m R88A-CAGB001-5SR-E 3 m R88A-CAGB003SR-E 5 m R88A-CAGB005SR-E 10 m R88A-CAGB010SR-E 15 m R88A-CAGB015SR-E 20 m R88A-CAGB020SR-E	
		with brake □-BS2 1.5 m R88A-CAKF001-5BR-E 3 m R88A-CAKF003BR-E 5 m R88A-CAKF005BR-E 10 m R88A-CAKF010BR-E 15 m R88A-CAKF015BR-E 20 m R88A-CAKF020BR-E	
	For 400 V servomotors R88M-K(3K0/4K0/5K0)30(F/C)□ R88M-K(3K0/4K0/5K0)20(F/C)□ R88M-K(2K0/3K0)10(F/C)□	without brake □-S2 1.5 m R88A-CAGD001-5SR-E 3 m R88A-CAGD003SR-E 5 m R88A-CAGD005SR-E 10 m R88A-CAGD010SR-E 15 m R88A-CAGD015SR-E 20 m R88A-CAGD020SR-E	
		with brake □-BS2 1.5 m R88A-CAGD001-5BR-E 3 m R88A-CAGD003BR-E 5 m R88A-CAGD005BR-E 10 m R88A-CAGD010BR-E 15 m R88A-CAGD015BR-E 20 m R88A-CAGD020BR-E	

Brake cable (for 3000 r/min 50-750 W Motors)

Symbol	Specifications	Model	Appearance
(6)	Brake cable only. For 200 V servo motors with brake R88M-K(050/100/200/400/750)30(H/T)-BS2	1.5 m R88A-CAKA001-5BR-E	
		3 m R88A-CAKA003BR-E	
		5 m R88A-CAKA005BR-E	
		10 m R88A-CAKA010BR-E	
		15 m R88A-CAKA015BR-E	
		20 m R88A-CAKA020BR-E	

Connectors for encoder, power and brake cables

Specifications	Applicable Servomotor	Model
Connectors for making encoder cables	Drive side (CN2) All models	R88A-CNW01R
	Motor side R88M-K(050/100/200/400/750)30(H/T)□	R88A-CNKO2R
	Motor side R88M-K(1K0/1K5)30(H/T)□ R88M-K(750/1K0/1K5/2K0/3K0/4K0/5K0)30(F/C)□ R88M-K(400/600/1K0/1K5/2K0/3K0/4K0/5K0)20□ R88M-K(900/2K0/3K0)10□	R88A-CNKO4R
Connectors for making power cables	Motor side R88M-K(050/100/200/400/750)30(H/T)□	R88A-CNKO11A
	Motor side R88M-K(1K0/1K5)30(H/T)-S2 R88M-K(1K0/1K5)20(H/T)-S2 R88M-K90010(H/T)-S2 R88M-K(750/1K0/1K5/2K0)30(F/C)-S2, R88M-K(400/600/1K0/1K5/2K0)20(F/C)-S2 R88M-K90010(F/C)-S2	MS3108E20-4S
	Motor side R88M-K(1K0/1K5)30(H/T)-BS2 R88M-K(1K0/1K5)20(H/T)-BS2 R88M-K90010(H/T)-BS2	MS3108E20-18S
	Motor side R88M-K(750/1K0/1K5/2K0/3K0/4K0/5K0)30(F/C)-BS2 R88M-K(400/600/1K0/1K5/2K0/3K0/4K0/5K0)20(F/C)-BS2 R88M-K900/2K0/3K0)10(F/C)-BS2	MS3108E24-11S
	Motor side R88M-K(3K0/4K0/5K0)30(F/C)-S2 R88M-K(3K0/4K0/5K0)20(F/C)-S2 R88M-K(2K0/3K0)10(F/C)-S2	MS3108E22-22S
Connector for brake cable	Motor side R88M-K(050/100/200/400/750)30(H/T)-BS2	R88A-CNKO11B

Note: 1. All cables listed are flexible and shielded (except the R88A-CAKA□□□-BR-E which is only a flexible cable).

2. All connectors and cables listed have IP67 class (except R88A-CNW01R connector and R88A-CRGD0R3C cable).

ALL DIMENSIONS SHOWN ARE IN MILLIMETERS.
To convert millimeters into inches, multiply by 0.03937. To convert grams into ounces, multiply by 0.03527.