## OMRON

# TYPE JX-A□

### **Model X200 Series Inverter**

Thank you for purchasing JX inverter.

To ensure safe operation, please be sure to read the safety precautions provided in this document along with all of the user manuals for the inverter. Please be sure you are using the most recent versions of the user manuals. Keep this instruction manual and all of the manuals in a safe location and be sure that they are readily available to the final user of the products

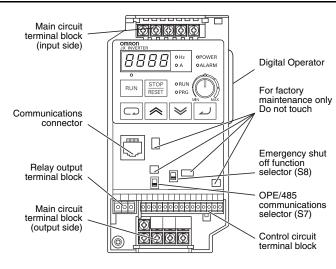
**INSTRUCTION MANUAL** 

| Name                    | Cat. No.   |
|-------------------------|------------|
| JX Series User's Manual | I567-E1-01 |

### **OMRON Corporation**

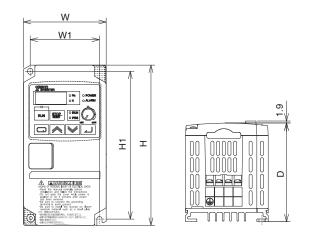
NT305X-1

#### Names of Parts



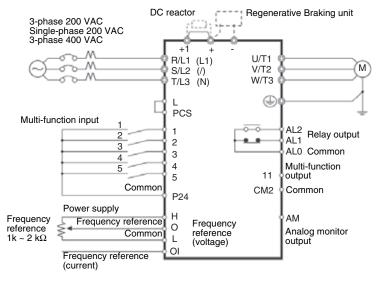
### **Installation and Wiring**

#### **■** Dimensions



| JX-  | w   | W1  | Н   | H1  | D     |
|--|-----|-----|-----|-----|-------|
| A2002-E, AB002-EF  | 80  | 67  | 155 | 143 | 95.5  |
| A2004-E, AB004-EF  |     |     |     |     | 109.5 |
| A2007-E  |     |     |     |     | 132.5 |
| A4004-EF, AB007-EF   | 110 | 98  | 189 | 176 | 130.5 |
| A2015-E, A2022-E, A2037-E<br>A4007-EF, A4015-EF, A4022-EF,<br>A4040-EF, AB015-EF, AB022-EF |     |     |     |     | 157.5 |
| A2055-E, A2075-E,<br>A4055-EF, A4075-EF  | 180 | 164 | 250 | 235 | 167.5 |

#### ■ Standard Connection Diagram



- \* Connect a single-phase 200 VAC input to terminals L1 and N.
- \* Factory default settings for relay output are NC contact for AL1 and NO contact for AL2.

#### ■ Terminal symbols, Screw size and Tightening Torque

| Туре               | Terminal symbol  | A2002 to A2007<br>AB002 to AB004  | A2015 to A2037<br>A4004 to A4037<br>AB007 to AB022 | A2055 to A2075<br>A4055 to A4075 |
|--------------------|--|-----------------------------------|--|----------------------------------|
| Main<br>circuit    | R/L1,S/L2,T/L3<br>U/T1, V/T2, W/T3<br>Ground<br>(symbol) | M3.5<br>0.8 N·m<br>(max. 0.9 N·m) | M4<br>1.2 N·m<br>(max. 1.3 N·m)                    | M5<br>3.0 N⋅m<br>(max. 3.3 N⋅m)  |
| Option             | -,+,+1   |                                   |  |                                  |
| Control<br>circuit | AM,H,O,OI,L<br>5, 4, 3, 2,1,L,<br>PCS,P24, CM2,11        | M2 /                              | 0.2 N⋅m (max. 0.25                                 | N·m)                             |
| Relay              | AL0,AL1,AL2  | M2.5 / 0.5 N·m (max. 0.6 N·m)     |  |                                  |
| Ground             | _  | M4 M5                             |  | M5                               |

<sup>\*</sup> For AB \( \subseteq \subseteq \), L1, /, N are indicated instead R/L1, S/L2, T/L3 respectively.

### Keys

|               | Name  | Description  |  |
|---------------|---|--|--|
|               |   | Switches between the command setting and the data settings, and between the basic function mode and the expended function mode.  |  |
|               |   | ■ Status transition  |  |
|               |   | $ \begin{array}{c c} 58.1 \\ \hline  & \bigcirc & \bigcirc & \bigcirc \\ \hline  & \bigcirc & \bigcirc \\ \hline  & \bigcirc & \bigcirc & \bigcirc \\ \hline  & \bigcirc & \bigcirc \\ \hline  & \bigcirc & \bigcirc & \bigcirc \\ \hline  & \bigcirc \\ \hline  & \bigcirc & \bigcirc \\ \hline  & \bigcirc \\$ |  |
|               |   | * Hold down the Mode key for 3 seconds to jump to 'd001'.  |  |
|               | Increment key   | Changes the set values, parameters and Commands.   |  |
| <b>*</b>      | Decrement key   |  |  |
| RUN           | RUN key Starts the operation. Forward/Reverse rotation depends on the 'F004' setting. |  |  |
| STOP<br>RESET | STOP/RESET<br>key   | Stops the operation. Functions as the Reset key if an error occurs.  |  |
| 2             | Enter key   | Enters and stores the data.  |  |

#### **Parameter List**

**Function name** 

Monitor or data range

Parameter

No

| No.             | . unotion numb  | monitor or data range   |
|-----------------|---|---|
| d001            | Output frequency monitor  | 0.0 to 400.0  |
| d002            | Output current monitor  | 0.0 to 999.9  |
| d003            | Rotation direction monitor  | F:forward/o:stop/r:reverse  |
| d004            | PID feedback value monitor  | 0.00 to 9999<br>(Valid when the PID function is selected.)  |
| d007            | Output frequency monitor (after conversion)                           | 0.00 to 9999<br>1000 to 3996 (at 10000 to 39960)<br>(Output frequency × conversion factor of b086                                     |
| d013            | Output voltage monitor  | 0 to 600  |
| d016            | Total RUN time  | 0 to 9999   |
| d017            | Power ON time monitor   | 0 to 9999   |
| d018            | Fin temperature monitor   | 0.0 to 200.0  |
| d080            | Fault frequency monitor   | 0 to 9999   |
| d081            | Fault monitor 1 (latest)  | Error code (condition of occurrence) $\rightarrow$  |
| d082            | Fault monitor 2   | Output frequency   Output current   Output current   Output current   |
| d083            | Fault monitor 3   | Internal DC voltage $\rightarrow$ RUN time $\rightarrow$ ON time  |
| d102            | DC voltage monitor  | 0.0 to 999.9  |
| d104            | Electric thermal monitor  | 0.0 to 100.0  |
| F001            | Output frequency set-<br>ting / monitor                               | Starting frequency to max. frequency  |
| F002/F202       | Acceleration time1/2nd acceleration time1                             | 0.01 to 3000  |
| F003/F203       | Deceleration time1/2nd deceleration time1                             | 0.01 to 3000  |
| F004            | Operator rotation direction selection                                 | 00:forward/01:reverse   |
| A001/A201       | Frequency reference<br>selection/2nd frequency<br>reference selection | 00:Digital Operator (volume)/01:Terminal/<br>02:Digital Operator (F001)/<br>03:Modbus communication/<br>10:Frequency operation result |
| A002/A202       | RUN command selection/2nd RUN command selection                       | 01:Terminal/02:Digital Operator/<br>03:Modbus communication   |
| A003/A203       | Base frequency/<br>2nd base frequency                                 | 30 to max. frequency [A004/A204]  |
| A004/A204       | Maximum frequency/<br>2nd maximum frequency                           | 30 to 400   |
| A005            | O/OI selection  | 02: Switch between O/Volume via terminal AT<br>03: Switch between OI/Volume via terminal AT<br>04: O input only/05:OI input only      |
| A020/A220       | Multi-step speed<br>reference0/2nd<br>multi-step speed<br>reference0  | 0.0/Starting frequency to max. frequency  |
| A021 to<br>A035 | Multi-step speed reference1~15  | 0.0/Starting frequency to max. frequency  |
| A038            | Jogging frequency   | 0.00/Strating frequency to 9.99   |
| A039            | Jogging stop selection  | 00:Free run on jogging stop<br>01:Deceleration stop on jogging stop<br>02:DC injection braking on jogging stop                        |
| A045/A245       | Output voltage gain/ 2nd output voltage gain                          | 20 to 100   |
| A097            | Acceleration pattern selection  | 00:Line/01:S-shape curve  |
| A098            | Deceleration pattern selection  |   |
| b001            | Retry selection   | 00: Alarm/01:0 Hz start<br>02: Frequency matching start<br>03: Trip after frequency matching deceleration<br>stop                     |
| b002            | Allowable momentary power interruption time                           | 0.3 to 25.0   |
| b083            | Carrier frequency   | 2.0 to 12.0   |
| b084            | Initialization selection  | 00:Clear the trip monitor 01:Initialize data  |
| b130            | Overvoltage LAD stop function   | 02:Clear and initialize 00:Disable/01:Enable  |
|                 | TUTTOLIOTT  |   |

| -               |  |   |
|-----------------|--|---|
| Parameter No.   | Function name  | Monitor or data range   |
| C001/C201       | Multi-function input1<br>selection/2nd<br>multi-function input1<br>selection | 00:FW(forward)/01:RV(reverse)/ 02:CF1(multi-step speed setting binary1)/ 03:CF2(multi-step speed setting binary2)/ 04:CF3(multi-step speed setting binary3)/  |
| C002/C202       | Multi-function input2<br>selection/2nd<br>multi-function input2<br>selection | 05:CF4(multi-step speed setting binary4)/ 06:JG(jogging)/07:DB(external DC injection/<br>braking)/08:SET(2nd control)/09:2CH(2-step<br>acceleration/deceleration)/11:FRS(free run<br>stop)/12:EXT(external trip)/13:USP(USP func-                                 |
| C003/C203       | Multi-function input3<br>selection/2nd<br>multi-function input3<br>selection | ion)/15:SFT(soft lock)/16:AT(analog input<br>switch)/18:RS(reset)/19:PTC(thermistor input)/<br>20:STA(3-wire start)/21:STP(3-wire stop)/22:F/<br>R(3-wire forward/reverse)/23:PID(PID enable/   |
| C004/C204       | Multi-function input4<br>selection/2nd<br>multi-function input4<br>selection | disable)/24:PIDC(PID integral/reset)/ 27:UP(UP/DWN function accelerated)/ 28:DWN(UP/DWN function decelerated)/ 29:UDC(UP/DWN function data clear)/  |
| C005/C205       | Multi-function input5<br>selection/2nd<br>multi-function input5<br>selection | 31:OPE(forward operator)/50:ADD(frequency addition)/51:F-TM(forced terminal block)/ 52:RDY(ready function)/53:SP-SET(special 2nd function)/64:EMR(emergency shut off)/ 255:No function  |
| C011 to<br>C015 | Multi-function input 1-5 operation selection                                 | 00:NO<br>01:NC  |
| C021            | Multi-function output terminal 11 selection                                  | 00:RUN(during RUN)/01:FA1(constant speed reached)/02:FA2(set frequency min. reached)/   |
| C026            | Relay output (AL1,AL2) function selection                                    | 03:OL(overload warning)/04:OD(PID excessive deviation)/05:AL(alarm output)/06:Dc(disconnection defected)/07:FBV(PID FB value output)/08:NDc(Network error)/09:LOG(logic operation output)/10:ODc(communication option, disconnected)/43:LOC(light load defection) |
| C028            | AM selection   | 00:Output frequency/01:Output current   |
| C031            | Multi-function output<br>Terminal 11 contact<br>selection                    | 00:NO contact at AL1, NC contact at AL2<br>01:NC contact at AL1, NO contact at AL2  |
| C036            | Relay output (AL1,AL2) contact selection                                     |   |
| H003/H203       | Motor capacity<br>selection/2nd motor<br>capacity selection                  | 200V class: 0.2 to 7.5<br>400V class: 0.4 to 7.5  |
| H004/H204       | Motor pole number<br>selection/2nd motor pole<br>number selection            | 2/4/6/8   |

### SUITABILITY FOR USE

OMRON shall not be responsible for conformity with any standards, code, or regulations that apply to the combination of products in the customer's application or use of the products.

Take all necessary steps to determine the suitability of the product for the systems, machines, and equipment with which it will be used. Please know and observe all prohibitions of use apllicable to the products.

NEVER USE THE PRODUCTS FOR AN APPLICATION INVOLVING SERI-OUS RISK TO LIFE OR PROPERTY WITHOUT ENSURING THAT THE SYSTEM AS A WHOLE HAS BEEN DESIGNED TO ADDRESS THE RISKS, AND THAT THE OMRON PRODUCTS ARE PROPERLY RATED AND IN-STALLED FOR THE INTENDED USE WITHIN THE OVERALL EQUIPMENT OR SYSTEM.

See also product catalogs for Warranty and Limitations of Liability.

Local support office:

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Note: In the interest of product improvement, specifications are subject to change without

Printed in Japan

#### **Safety Precautions**

#### ■ Indications and Meanings of Safety Information

In this user's manual, the following precautions and signal words are used to provide information to ensure the safe use of the JX Inverter. The information provided here is vital to safety. Strictly observe theprecautions provided.

#### ■ Meanings of Signal Words



ndicates an imminently hazardous situation which if not avoided, is likely to result in serious injury or may result in death. Additionally there may be evere property damage.



ndicates a potentially hazardous situation which, if not avoided, may result in minor or moderate injury or in property damage.

#### ■ Alert Symbols in this Document

### **△** DANGER



Turn off the power supply and implement wiring correctly. Not doing so may esult in a serious injury due to an electric shock.



Wiring work must be carried out only by qualified personnel. Not doing so nany result in a serious injury due to an electric shock.



Be sure to ground the unit. Not doing so may result in a serious injury due to an electric shock or fire. (200 V class: type-D grounding, 400 V class: type-C grounding)



Do not remove the front cover during the power supply and 5 minutes after ne power shut off. Doing so may result in a serious injury due to an electric



Do not operate the Operator or switches with wet hands. Doing so may result a serious injury due to an electric shock.



nspection of the Inverter must be conducted after the power supply has been urned off. Not doing so may result in a serious injury due to an electric shock.

The main power supply is not necessarily shut off even if the emergency shut



Do not change wiring, mode change switches (S7, S8), optional devices or eplace cooling fans while power is being supplied. Doing so may result in a serious injury due to an electric shock.



Do not connect resistors to the terminals (+1, +, -) directly Doing so might result in a small-scale fire, heat generation or damage to the

**△** CAUTION



nstall a stop motion device to ensure safety. Not doing so might result in a ninor injury. (A holding brake is not a stop motion device designed to ensure safetv.)



Be sure to use a specified type of braking resistor/regenerative braking unit. n case of a braking resistor, install a thermal relay that monitors the temperature of the resistor. Not doing so might result in a moderate burn due to the eat generated in the braking resistor/regenerative braking unit. Configure a equence that enables the Inverter power to turn off when unusual overheatng is detected in the braking resistor/regenerative braking unit.



he Inverter has high voltage parts inside which, if short-circuited, might cause damage to itself or other property. Place covers on the openings or ake other precautions to make sure that no metal objects such as cutting bits or lead wire scraps go inside when installing and wiring. Do not touch the Inverter fins, braking resistors and the motor, which become

too hot during the power supply and for some time after the power shut off.



loing so may result in a burn. Take safety precautions such as setting up a molded-case circuit reaker(MCCB) that matches the Inverter capacity on the power supply side. Not doing so might result in damage to property due to the short circuit of the



Do not dismantle, repair or modify this product. oing so may result in an injury.

#### **Precautions for Safe Use**

■ Installation and Storage

Do not store or use the product in the following places.

- · Locations subject to direct sunlight.
- Locations subject to ambient temperature exceeding the
- Locations subject to relative humidity exceeding the specifications.
- Locations subject to condensation due to severe temperature fluctuations
- Locations subject to corrosive or flammable gases.
- Locations subject to exposure to combustibles
- · Locations subject to dust (especially iron dust) or salts.
- · Locations subject to exposure to water, oil, or chemicals.
- · Locations subject to shock or vibration.

#### ■ Transporting, Installation, and Wiring

- Do not drop or apply strong impact on the product. Doing so may result in damaged
- · Do not hold by the front cover, but hold by the fins during transportation.
- Do not connect an AC power supply voltage to the control input/output terminals. Doing so may result in damage to the product.
- Be sure to tighten the screws on the terminal block securely. Wiring work must be done after installing the unit body.
- . Do not connect any load other than a three-phase inductive motor to the U, V, and W output terminals.
- Take sufficient shielding measures when using the product in the following locations. Not doing so may result in damage to the product.
- · Locations subject to static electricity or other forms of noise.
- · Locations subject to strong magnetic fields.
- Locations close to power lines.

#### ■ Operation and Adjustment

- · Be sure to confirm the permissible range of motors and machines before operation because the inverter speed can be changed easily from low to high
- Provide a separate holding brake if necessary.

#### ■ Maintenance and Inspection

Be sure to confirm safety before conducting maintenance, inspection or parts replace-

#### **Precautions for Correct Use**

#### ■ Installation

. Mount the product vertically on a wall or on a DIN Rail (optional) with the product's longer sides upright The material of the wall has to be noninflammable such as a metal plate.

#### ■ Main Circuit Power Supply

. Confirm that the rated input voltage of the Inverter is the same as AC power supply volt-

#### ■ Error Retry Function

- Do not come close to the machine when using the error retry function because the machine may abruptly start when stopped by an alarm
- · Be sure to confirm the RUN signal is turned off before resetting the alarm because the machine may abruptly start

#### ■ Non-Stop Function at Momentary Power Interruption

 Do not come close to the machine when selecting reset in the non-stop function at momentary power interruption selection (b050) because the machine may abruptly start after the power is turned on.

#### ■ Operation Stop Command

- Provide a separate emergency stop switch because the STOP Key on the Operator is valid only when function settings are performed.
- · When checking a signal during the power supply and the voltage is erroneously applied to the control input terminals, the motor may start abruptly. Be sure to confirm safety before checking a signal.

#### ■ Product Disposal

• Comply with the local ordinance and regulations when disposing of the product.

#### **UL Cautions**

The warnings and instructions in this section summarizes the procedures necessary to ensure an inverter installation complies with Underwriters Laboratories guidelines

• Use 60/75°C Cu wire only or equivalent.

 $(For\ models: X200-015L(A2015),\ -022L(A2022),\ -037L(A2037),\ -055L(A2055),$ -075L(A2075), -007S(AB007), -015S(AB015), -022S(AB022))

Use 75°C Cu wire only or equivalent.

(For models: X200-002L(A2002), -004L(A2004), -007L(A2007), -022H(A4022), -040H(A4040), -055H(A4055), -075H(A4075), -002S(AB002), -004S(AB004))

• Use 60°C Cu wire only or equivalent.

(For models: X200-004H(A4004), -007H(A4007), -015H(A4015))

- Open Type Equipment.
- Suitable for use on a circuit capable of delivering not more than 100k rms symmetrical amperes, 240 V maximum when protected by Class CC, G, J or R fuses or circuit break er having an interrupting rating not les than 100,000 rms symmetrical amperes, 240 volts maximum. (For models: 200 V class)
- Suitable for use on a circuit capable of delivering not more than 100k rms symmetrical amperes, 480 V maximum when protected by Class CC, G, J or R fuses or circuit breaker having an interrupting rating not les than 100,000 rms symmetrical amperes, 480 volts maximum (For models: 400 V class)
- Install device inn pollution degree 2 environment.
- Maximum Surrounding Air Temperature 50°C or equivalent.
- Caution-Risk of electric shock, -capacitor discharge time is at least 5 minutes.
- Solid state motor overload protection is provided in each model
- Integral solid state short circuit protection does not provide branch circuit protection. Branch circuit protection must be provided in accordance with the National Electric Code and any additional local codes or equivalent.

#### ■ Terminal Tightening Torque and Wire Size

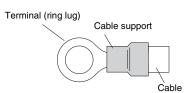
The wire size range and tightening torque for field wiring terminals are presented in the tables below

| Input       | Motor Output |       | Inverter Model                | Power Terminal             | Torque  |       |
|-------------|--------------|-------|-------------------------------|----------------------------|---------|-------|
| Voltage     | kW           | HP    | X200- (JX-)                   | Wiring Size<br>Range (AWG) | Ft-lbs  | (N·m) |
| 200 V class | 0.2          | 1/4   | 002LFRF/SFEF<br>(A2002/AB002) | 14<br>(75°C only)          | 0.6     | 0.8   |
|             | 0.4          | 1/2   | 004LFRF/SFEF<br>(A2004/AB004) |                            |         |       |
|             | 0.75         | 1     | 007LFRF/SFEF<br>(A2007/AB007) |                            | 0.9     | 1.2   |
|             | 1.5          | 2     | 015LFRF/SFEF<br>(A2015/AB015) | 12                         |         |       |
|             | 2.2          | 3     | 022LFRF/SFEF<br>(A2022/AB022) | 10                         |         |       |
|             | 3.7          | 5     | 037LFRF<br>(A2037)            |                            |         |       |
|             | 5.5          | 7 1/2 | 055LFRF<br>(A2055)            | 8                          | 2.3 3.0 | 3.0   |
|             | 7.5          | 10    | 075LFRF<br>(A2075             |                            |         |       |
| 400 V class | 0.4          | 1/2   | 004HFEF<br>(A4004)            | 16<br>(60°C only)          | 0.9     | 1.2   |
|             | 0.75         | 1     | 007HFEF<br>(A4007)            |                            |         |       |
|             | 1.5          | 2     | 015HFEF<br>(A4015)            |                            |         |       |
|             | 2.2          | 3     | 022HFEF<br>(A4022)            | 14<br>(75°C only)          |         |       |
|             | 4            | 5     | 040HFEF<br>(A4040)            |                            |         |       |
|             | 5.5          | 7 1/2 | 055HFEF<br>(A4055)            | 10                         | 2.3     | 3.0   |
|             | 7.5          | 10    | 075HFEF<br>(A4075)            |                            |         |       |

| Tarminal Canastar           | Wining Cine Benge (AWC) | Torque    |           |  |
|-----------------------------|-------------------------|-----------|-----------|--|
| Terminal Conector           | Wiring Size Range (AWG) | Ft-lbs    | (N·m)     |  |
| Logic and Analog connectors | 30-16                   | 0.16-0.19 | 0.22-0.25 |  |
| Relay connector             | 30-14                   | 0.37-0.44 | 0.5-0.6   |  |

#### ■ Wire Connectors

Field wiring connections must be made by a UL Listed and CSA certified ring lug terminal connector sized for the wire gauge being used. The connector must be fixed using the crimping tool specified by the connector manufacturer.



#### ■ Circuit breaker and Fuse Size

The Inverter's connections to input power must include UL Listed inverse time circuit breakers with 600 V rating, or UL Listed fuses as shown in the table below.

| Input<br>Voltage | Inverter Model<br>X200-<br>(JX-) | Circuit Breaker/Fuse        | Ratings (A) |
|------------------|----------------------------------|-----------------------------|-------------|
| 200V class       | 002LFRF/SFEF<br>(A2002/AB002)    | Inverse timecircuit Breaker | 10          |
|                  | 004LFRF/SFEF<br>(A2004/AB004)    |                             |             |
|                  | 007LFRF/SFEF<br>(A2007/AB007)    |                             | 15          |
|                  | 015LFRF/SFEF<br>(A2015/AB015)    |                             | 20          |
|                  | 022LFRF/SFEF<br>(A2022/AB022)    |                             | 30          |
|                  | 037LFRF<br>(A2037)               |                             |             |
|                  | 055LFRF<br>(A2055)               |                             | 40          |
|                  | 075LFRF<br>(A2075                |                             | 50          |
| 400V class       | 004HFEF<br>(A4004)               | Distribution Fuse (Class J) | 3           |
|                  | 007HFEF<br>(A4007)               |                             | 6           |
|                  | 015HFEF<br>(A4015)               |                             | 10          |
|                  | 022HFEF<br>(A4022)               |                             |             |
|                  | 040HFEF<br>(A4040)               |                             | 15          |
|                  | 055HFEF<br>(A4055)               |                             | 20          |
|                  | 075HFEF<br>(A4075)               |                             | 25          |

#### ■ Motor Overload Protection

JX Inverters provide solid state motor overload protection, which depends on the proper setting of the following parameters:

- b012: electronic overload protection
- b212: electronic overload protection, 2nd motor

Set the rated current [Amperes] of the motor(s) with the above parameters. The setting range is 0.2 rated current to 1.0 rated current.

When two or more motors are connected to the Inverter, they cannot be protected by the electronic overload protection. Install an external thermal relay on each motor.

#### **Conformance to EC Directives**

- For earthing, selection of cable, and any other conditions for EMC-compliance, please refer to the manual for installation.
- This is a class A product in residential areas it may cause radio interference, in which case the user may be required to take adequate measures to reduce interference.

#### JX series Inverter has integrated EMC filter as shown below

• 200 V class: EN61800-3 category C1 • 400 V class: EN61800-3 category C2

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