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Integrated control software for F150-3

Vision Composer

"Vision Composer" control software makes it easy to achieve the optimum inspection in flowchart format



Vision Composer

Features

Revolutionizing inspection based on image processing

Although visual sensors can be used based on simple menu settings, they have tended to lack functionality. On the other hand, full-featured advanced image processing devices are capable of a variety of functions, but special programming is necessary. The Vision Conposer makes it easy to achieve the optimum inspection in flowchart format.



Features

A flexible processing flow can be created in Windows.

Individual position corrections inside each area Supports individual position corrections inside each inspection area.



Enhanced screen editing functions increase ease of use.

Editing of scene names Scene data can be saved using a name that describes the inspection for easy searching and management. Scene data, "no good" images, and other data can be exchanged between the F150 and a computer.

sfer data from PC to controller.	
Choose the desired process.	HOPC+Controller Controller+PC
Select file to transfer.	
Scene Inspection1 System Scene Scene number Svs + Scn	00 Vote >>

Freely create the measurement screen.



etc.) in any position Display a line segment linking

Reduced display of measurement results

The menu screen can also be edited.

A text editor can be used to change the names and show/hide of menu items.



Speed bar

software program.

Frequently used processing tasks can be displayed as icons on the toolbar. Smoother operation.



The type of inspection can be changed by model based on the results of model sorting.



Manage measurement results on a computer. Measurement results can be transferred to a computer, making it possible to manage and process data using a spreadsheet or other



Record the date and time of defect occurrences

- Print out each day's inspection data.
- Transfer inspection data over a network
- Use a spreadsheet or other tool for statistical processing.

Print and output files of flowcharts and processing setting lists.

Settings can be verified at a glance.

Import data into a word processor program for easy creation of reports.



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Operation procedure





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List of processing items		
Image input related	Camera image input	Input images from the camera
	Memory image input	Input an image from the storage memory to the image memory
	Image transfer	Transfer an image between image memories. Enables multi-stage pre-processing and background cut-off.
Postion correction related	Scrolling	Image scrolling for position correction
	One-unit scrolling	Easy position correction (using one unit)
	Two-unit scrolling Scrolling reset	Easy position correction (using two units) Resets scrolled image memory to original position
General measurement related	Binary area	Obtains only binary area at high speed
	Binary center of gravity and area	Obtains binary center of gravity and area
	Bbinary center of gravity and main axis angle	Obtains binary center of gravity, area, and main axis angle
	Dark-light search	Searches stored model images
	High-precision search	Searches the stored model images and obtains the search coordinates in sub-pixel units.
	Damage and dirt (linear)	Inspects for damage and dirt on a straight line
	Damage and dirt (circular)	Inspects for damage and dirt on a circle
	Damage and dirt (circular arc)	Inspects for damage and dirt on a circular arc
	Damage and dirt (rectangular)	Inspects for damage and dirt inside a rectangular area
	Dark-light edge position	Obtains the edge position by dark-light processing
	Dark-light edge number	Obtains the number of objects by dark-light edge detection processing.
	Dark-light edge width	Obtains the distance between two edges
	Darkness average/deviation	Obtains the average darkness and deviation of a specified area
	Rotation search	Searches objects that are rotated.
	Obtains angle of circular object	Obtains the angle of a circular object at high speed
	Sorting	Sorts up to eight models
	Model dictionary	Used with "Sort 2"; up to 16 types are sorted

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	Sort 2	Used with "Model dictionary"; up to 16 types are sorted	
General measurement related	Labeling	Obtains the number of objects by label processing.	
	Label sorting	Rearranging based on the label area and center of gravity of each object	
	Label data	Obtains the area and center of gravity of each label	
	Edge code	Generates an edge code image as a preprocessing step for execution of a circle search or high-pre- cision circle search.	
	Circle search	Searches for circular objects	
	Stable circle search	Stable circle search without regard to the size of the circle.	
	High-precision circle search	Searches for circular objects and obtains the search coordinates on the order of sub-pixels.	
Measurement supplement re- lated	Computation	Based on the selected computation equation, computations are carried out using the measurement results of each processing item.	
	Calibration	Converts camera coordinates to actual coordinates	
	Obtains processing unit data	References parameter settings of processing unit	
	Processing unit data settings Elapsed time	The parameter settings of the processing unit can be changed as desired Obtains the elapsed time after input of the measurement trigger.	
	Wait	Processing waits during the specified time	
Branch control related	Condition-based branching	Processing is divided into branches based on the specified conditions	
	DI input branching	Processing is divided into branches based on input from the terminal block	
	End	Ends processing	
	DO decision output	Outputs the measurement decision result to the terminal block.	
	DO data output	Outputs measurement data to the terminal block	
Result output related	RS-232C data output	Outputs measurement data to the RS-232C	
	RS-232C data output 2	Outputs data in a free format to the RS-232C	
	Higher link data output	Outputs data using the higher link protocol	
	Data locking output	Outputs data for locking the measurement result in Vision Composer to the RS-232C	
	Value display	Displays any value in any position on the screen (for customization of the measurement screen)	
	Value display (small font)	Displays a value in a small font on the screen (for customization of the measurement screen)	
Result display related	Line display	Displays a line of any length in any position on the screen (for customization of the measurement screen)	
	Rectangle display	Displays a rectangle of any size in any position on the screen (for customization of the measurement screen)	
	Circle display	Displays a circle of any size in any position on the screen (for customization of the measurement screen)	
	Cross-hair cursor display	Displays a cross-hair cursor in any position on the screen (for customization of the measurement screen)	
Operating environment	·		
OS	Windows 95/98/NT 4.0 Japanese version (does not operate in Windows 3.1/NT3.5/2000)		
WWW browser	Microsoft Internet Explorer 4.0	or higher	
CPU	Pentium II 266 MHz or higher		
Memory	64 MB or higher (recommended)		
Free hard disk space	50 MB or higher		
Display image	1024 x 768 dots 256 colors or higher		
CD-ROM drive	4 x or higher		

ALL DIMENSIONS SHOWN ARE IN MILLIMETERS.

To convert millimeters into inches, multiply by 0.03937. To convert grams into ounces, multiply by 0.03527.

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